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ALTERNATE DERIVATION OF THE ANGULAR MOMENTUM EQUATION FOR INTERACTING PARTICLES

13.1 Alternate Derivation of the Angular Momentum Equation for Interacting Particles

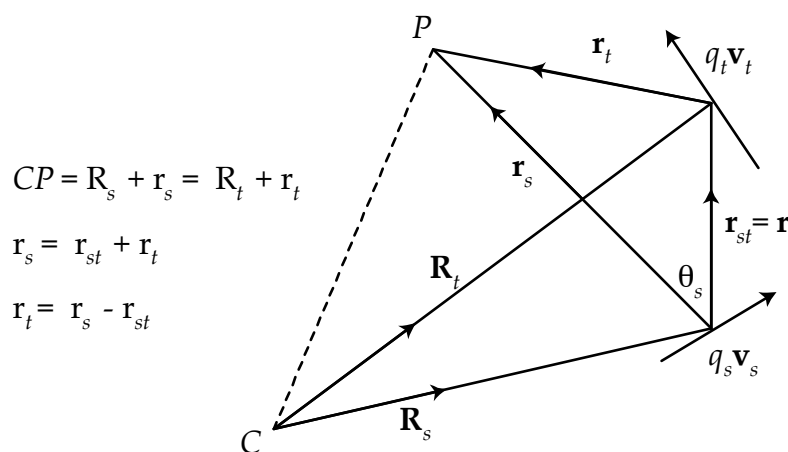


Fig. 13.

The electromagnetic linear momentum density, \mathbf{g}_{Tl} , delivered to the field at point P by $q_s \mathbf{v}_s$ and $q_t \mathbf{v}_t$ is

$$\begin{aligned}
 \mathbf{g}_{Tl} &= \varepsilon_0 (\mathbf{E}_s + \mathbf{E}_t) \times (\mathbf{B}_s + \mathbf{B}_t) \\
 &= \varepsilon_0 (\mathbf{E}_s \times \mathbf{B}_s + \mathbf{E}_s \times \mathbf{B}_t + \mathbf{E}_t \times \mathbf{B}_s + \mathbf{E}_t \times \mathbf{B}_t)
 \end{aligned} \tag{13.1}$$

The mutual linear electromagnetic momentum density, \mathbf{g}_ℓ , at a field point P is

$$\mathbf{g}_\ell = \varepsilon_0 (\mathbf{E}_s \times \mathbf{B}_t + \mathbf{E}_t \times \mathbf{B}_s) = \mathbf{g}_{\ell 1} + \mathbf{g}_{\ell 2} \quad (13.2)$$

$$\mathbf{B}_s = \frac{\mu_0 q_s \mathbf{v}_s \times \mathbf{r}_s}{4\pi r_s^3} = \frac{q_s}{4\pi \varepsilon_0 c^2} \frac{\mathbf{v}_s \times \mathbf{r}_s}{r_s^3} \quad \mathbf{E}_s = \frac{q_s}{4\pi \varepsilon_0} \frac{\mathbf{r}_s}{r_s^3} \quad (13.3)$$

$$\mathbf{B}_t = \frac{q_t}{4\pi \varepsilon_0 c^2} \frac{\mathbf{v}_t \times \mathbf{r}_t}{r_t^3} \quad \mathbf{E}_t = \frac{q_t}{4\pi \varepsilon_0} \frac{\mathbf{r}_t}{r_t^3} \quad (13.4)$$

\mathbf{r}_s and \mathbf{r}_t are distances from q_s and q_t , respectively, to the field point P , Fig. 13.1. Subscripts $\ell 1$ and $\ell 2$ refer to the linear momenta of the first and second terms respectively in Eq. (13.2).

The strength of \mathbf{B}_s and \mathbf{B}_t goes as $1/c^2$. Velocity correction to \mathbf{E}_s and \mathbf{E}_t will be required to include terms in $1/c^2$.

In general, for arbitrary multivectors q_s and q_t , the linear momentum density delivered to the field is:

$$\mathbf{g}_\ell = \frac{\varepsilon_0 [\mathbf{r}_s \times (\mathbf{v}_t \times \mathbf{r}_t) + \mathbf{r}_t \times (\mathbf{v}_s \times \mathbf{r}_s)] (q_s q_t + q_t q_s)}{(4\pi \varepsilon_0)^2 c^2} = \mathbf{g}_{\ell 1} + \mathbf{g}_{\ell 2}$$

let

$$q_t q_s \varepsilon_0 / (4\pi \varepsilon_0)^2 c^2 = k$$

$$\begin{array}{ccccccc} \mathbf{E}_s & \mathbf{B}_t & \mathbf{E}_t & \mathbf{B}_s & \mathbf{E}_s \times \mathbf{B}_t & \mathbf{E}_t \times \mathbf{B}_s & \\ \mathbf{r}_s \times (\mathbf{v}_t \times \mathbf{r}_t) + \mathbf{r}_t \times (\mathbf{v}_s \times \mathbf{r}_s) & = & \mathbf{v}_t (\mathbf{r}_s \cdot \mathbf{r}_t) - \mathbf{r}_t (\mathbf{r}_s \cdot \mathbf{v}_t) + \mathbf{v}_s (\mathbf{r}_t \cdot \mathbf{r}_s) - \mathbf{r}_s (\mathbf{r}_t \cdot \mathbf{v}_s) \end{array}$$

Relative to the point C , the position vector of the field point P is

$$CP = \mathbf{R}_s + \mathbf{r}_s = \mathbf{R}_t + \mathbf{r}_t \quad (13.5)$$

The total angular momentum is

$$\mathbf{G} = \int \mathbf{g}_\ell d\tau = \int (\mathbf{R}_s + \mathbf{r}_s) \mathbf{g}_{\ell 1} d\tau + \int (\mathbf{R}_t + \mathbf{r}_t) \mathbf{g}_{\ell 2} d\tau \quad (13.6)$$

using $\mathbf{R}_s + \mathbf{r}_s = \mathbf{R}_t + \mathbf{r}_t$.

The integration must be over all space. We have already integrated the linear momentum density \mathbf{g}_ℓ over all space to obtain the total linear momentum, \mathbf{G}_ℓ . It is

$$\mathbf{G}_\ell = \int \mathbf{g}_\ell d\tau = \frac{1}{4\pi \varepsilon_0 c^2} \frac{1}{2} \left[\frac{\mathbf{v}_t}{r} + \frac{(\mathbf{v}_t \cdot \mathbf{r}_{st}) \mathbf{r}_{st}}{r^3} \right]_{\ell 1} + \frac{\mathbf{v}_s}{r} + \frac{(\mathbf{v}_s \cdot \mathbf{r}_{st}) \mathbf{r}_{st}}{r^3} \Big|_{\ell 2} (q_s q_t + q_t q_s) / 2 \quad (13.7)$$

We now evaluate the second term in Eq. (13.6) by integrating it over all space. That is, we evaluate

$$\int (\mathbf{R}_s + \mathbf{r}_s) \times \mathbf{g}_{tsl}^{\varepsilon_0(\mathbf{E}_t \times \mathbf{B}_s)} d\tau = \frac{q_t q_s \varepsilon_0}{(4\pi\varepsilon_0)^2 c^2} \int (\mathbf{R}_s + \mathbf{r}_s) \times \frac{[\mathbf{v}_s (\mathbf{r}_s \cdot \mathbf{r}_t) - \mathbf{r}_s (\mathbf{r}_t \cdot \mathbf{v}_s)]}{r_s^3 r_t^3} d\tau \quad (q_s q_t + q_t q_s)/2 \quad (13.8)$$

For gravity, multiply Eqs. (13.7) and (13.8) by $(q_s q_t + q_t q_s)/2 = (P_s P_t + P_t P_s)/2$. We have already evaluated the two integrals

$$\int \mathbf{g}_{tsl}^{\varepsilon_0(\mathbf{E}_t \times \mathbf{B}_s)} d\tau = \frac{q_s q_t}{4\pi\varepsilon_0} \frac{1}{2c^2} \left(\frac{\mathbf{v}_s}{r} + \frac{\mathbf{v}_s \cdot \mathbf{r}_{st}}{r^3} \right) \quad (13.9)$$

$$\text{and} \quad \int \mathbf{g}_{stl}^{\varepsilon_0(\mathbf{E}_s \times \mathbf{B}_t)} d\tau = \frac{q_s q_t}{4\pi\varepsilon_0} \frac{1}{2c^2} \left(\frac{\mathbf{v}_t}{r} + \frac{\mathbf{v}_t \cdot \mathbf{r}_{st}}{r^3} \right) \quad (13.10)$$

Thus

$$\int (\mathbf{R}_s + \mathbf{r}_s) \times \mathbf{g}_{tsl}^{\varepsilon_0(\mathbf{E}_t \times \mathbf{B}_s)} d\tau = \frac{q_t q_s}{4\pi\varepsilon_0} \mathbf{R}_s \times \frac{1}{2c^2} \left(\frac{\mathbf{v}_s}{r} + \frac{(\mathbf{v}_s \cdot \mathbf{r}_{st}) \mathbf{r}_{st}}{r^3} \right) + \frac{q_t q_s}{(4\pi\varepsilon_0)^2} \frac{\varepsilon_0}{c^2} \int \frac{(\mathbf{r}_s \times \mathbf{v}_s) (\mathbf{r}_s \cdot \mathbf{r}_t)}{r_s^3 r_t^3} d\tau \quad (13.11)$$

In Eq. (13.11), $\mathbf{r}_s \cdot \mathbf{r}_t = (r_s^2 + r_t^2 - r_{st}^2)/2$.

We now evaluate the second term in Eq. (13.11).

$$\frac{q_t q_s}{(4\pi\varepsilon_0)^2} \frac{\varepsilon_0}{c^2} \int \frac{(\mathbf{r}_s \times \mathbf{v}_s) (r_s^2 + r_t^2 - r_{st}^2)/2}{r_s^3 r_t^3} d\tau \quad (13.12)$$

In general, replace $q_s q_t$ by $(q_s q_t + q_t q_s)/2$.

For gravity, $(q_s q_t + q_t q_s)/2 = (P_s P_t + P_t P_s)/2$ where $P_s = c\mathbf{e}_0 + \mathbf{v}_s$ and $P_t = c\mathbf{e}_0 + \mathbf{v}_t$.

$$\mathbf{r}_s \times \mathbf{v}_s = r_s \begin{vmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \mathbf{e}_3 \\ \sin \theta \cos \varphi & \sin \theta \sin \varphi & \cos \theta \\ \mathbf{v}_{sx} & \mathbf{v}_{sy} & \mathbf{v}_{sz} \end{vmatrix}$$

$$\begin{aligned} \mathbf{r}_s \times \mathbf{v}_s &= r_s [\mathbf{e}_1 (v_{sz} \sin \theta \cos \varphi - v_{sy} \cos \theta) + \mathbf{e}_2 (v_{sx} \cos \theta - v_{sz} \sin \theta \cos \varphi) \\ &\quad + \mathbf{e}_3 (v_{sy} \sin \theta \cos \varphi - v_{sx} \sin \theta \sin \varphi)] \end{aligned}$$

$$\begin{aligned}
(\mathbf{r}_s \times \mathbf{v}_s)(\mathbf{r}_t \cdot \mathbf{r}_s) &= r_s \left[\mathbf{e}_1 \left(\underline{v_{sz} \sin \theta \cos \varphi} - \underline{v_{sy} \cos \theta} \right) \right] \\
&\quad + \mathbf{e}_2 \left[\underline{v_{sx} \cos \theta} - v_{sz} \sin \theta \cos \varphi \right] \\
&\quad + \mathbf{e}_3 \left[v_{sy} \sin \theta \cos \varphi - v_{sx} \sin \theta \sin \varphi \right] \frac{(r_s^2 + r_t^2 - r^2)}{2} \quad (13.13)
\end{aligned}$$

$$d\tau = (r_s r_t / r_{st}) dr_t dr_s d\varphi = r_{st}^3 \rho_s \rho_t d\rho_s d\rho_t d\varphi.$$

When Eq. (13.13) is integrated over φ , only the underlined terms are non-zero. The result is

$$(\mathbf{r}_s \times \mathbf{v}_s)(\mathbf{r}_t \cdot \mathbf{r}_s) = 2\pi r_s [-\mathbf{e}_1 v_{sy} \cos \theta + \mathbf{e}_2 v_{sx} \cos \theta] (r_s^2 + r_t^2 - r_{st}^2) / 2$$

In dimensionless variables, $r_s = r_{st} \rho_s$, $r_t = r_{st} \rho_t$

$$\begin{aligned}
(\mathbf{r}_s \times \mathbf{v}_s)(\mathbf{r}_t \cdot \mathbf{r}_s) &= -2\pi r_{st}^2 [\mathbf{e}_1 v_{sy} - \mathbf{e}_2 v_{sx}] r_s \cos \theta (\rho_s^2 + \rho_t^2 - 1) / 2 \\
&= -2\pi r_{st}^3 (\mathbf{v}_s \times \mathbf{e}_3) \rho_s \cos \theta (\rho_s^2 + \rho_t^2 - 1) / 2 \quad (13.14)
\end{aligned}$$

Now evaluate

$$\rho_s \cos \theta [(1 + \rho_s^2) - \rho_t^2], \quad \cos \theta = [(1 + \rho_s^2) - \rho_t^2] / 2\rho_s$$

First evaluate $\rho_s \cos \theta (\rho_s^2 - 1)$

$$\begin{aligned}
&\int_0^1 \int_{1-\rho_s}^{1+\rho_s} \frac{\rho_s \cos \theta (\rho_s^2 - 1)}{\rho_s^2 \rho_t^2} d\rho_s d\rho_t = \int_0^1 \int_{1-\rho_s}^{1+\rho_s} \frac{(\rho_s^2 - 1) [(1 + \rho_s^2) - \rho_t^2]}{\rho_s^2 \rho_t^2 2\rho_s} d\rho_s d\rho_t \\
&= \int_0^1 \int_{1-\rho_s}^{1+\rho_s} \left[\frac{(\rho_s^2 - 1)(\rho_s^2 + 1)}{2\rho_s^2 \rho_t^2} - \frac{(\rho_s^2 - 1)\rho_t^2}{2\rho_s^2 \rho_t^2} \right] d\rho_s d\rho_t \\
&= \int_0^1 \left[\frac{(\rho_s^2 - 1)(\rho_s^2 + 1) 2\rho_s}{2\rho_s^2 (1 - \rho_s^2)} - \frac{(\rho_s^2 - 1) 2\rho_s}{2\rho_s^2} \right] d\rho_s \\
&= \int_0^1 \left[\frac{-(\rho_s^2 + 1) 2\rho_s - 2\rho_s^2 + 2\rho_s}{2\rho_s^2} \right] d\rho_s = \int_0^1 \left[\frac{-2\rho_s^3 - 2\rho_s - 2\rho_s^3 + 2\rho_s}{2\rho_s^2} \right] d\rho_s \\
&= \int_0^1 \frac{-4\rho_s^3}{2\rho_s^2} d\rho_s = \int_0^1 -2\rho_s d\rho_s = [-\rho_s^2]_0^1 = -1 \quad (13.15)
\end{aligned}$$

Now evaluate

$$\begin{aligned}
 & \int_0^1 \int_{1-\rho_s}^{1+\rho_s} \frac{\rho_s \cos \theta \rho_t^2}{\rho_s^2 \rho_t^2} d\rho_t d\rho_s = \int_0^1 \int_{1-\rho_s}^{1+\rho_s} \frac{1}{\rho_s^2} \left[\frac{(1 + \rho_s^2) - \rho_t^2}{2\rho_t^2} \right] d\rho_t d\rho_s \\
 &= \int_0^1 \int_{1-\rho_s}^{1+\rho_s} \frac{1}{\rho_s^2} \frac{1}{2} \left[\frac{1 + \rho_s^2}{\rho_t^2} - 1 \right] d\rho_t d\rho_s \\
 &= \int_0^1 \frac{1}{\rho_s^2} \left[\frac{(1 + \rho_s^2)}{1 - \rho_s^2} - \frac{2\rho_s}{1 - \rho_s^2} \right] d\rho_s = \int_0^1 \frac{2}{\rho_s^2} \left[\frac{\rho_s + \rho_s^3 - \rho_s + \rho_s^3}{1 - \rho_s^2} \right] d\rho_s \\
 &= \int_0^1 \frac{1}{\rho_s^2} \frac{2\rho_s^3 d\rho_s}{1 - \rho_s^2} = \int_0^1 \frac{2\rho_s d\rho_s}{1 - \rho_s^2} \tag{13.16}
 \end{aligned}$$

$$\therefore \int_0^1 \int_{1-\rho_s}^{1+\rho_s} \cos \theta [(\rho_s^2 - 1) + \rho_t^2] \frac{d\rho_s d\rho_t}{\rho_s^2 \rho_t^2} = -1 + 1 = 0 \tag{13.17}$$

Now evaluate

$$\begin{aligned}
 & \int_1^\infty \int_{\rho_s-1}^{\rho_s+1} \frac{\rho_s \cos \theta (\rho_s^2 - 1)}{\rho_s^2 \rho_t^2} d\rho_s d\rho_t \\
 &= \int_1^\infty \int_{\rho_s-1}^{\rho_s+1} \left[\frac{(\rho_s^2 - 1)(\rho_s^2 + 1)}{2\rho_s^2 \rho_t^2} - \frac{(\rho_s^2 - 1)\rho_t^2}{2\rho_s^2 \rho_t^2} \right] d\rho_s d\rho_t \\
 &= \int_1^\infty \left[\frac{(\rho_s^2 - 1)(\rho_s^2 + 1)2}{2\rho_s^2(\rho_s^2 - 1)} - \frac{(\rho_s^2 - 1)}{2\rho_s^2} \right] d\rho_s \\
 &= \int_1^\infty \left[\frac{(\rho_s^2 + 1)}{\rho_s^2} - \frac{(\rho_s^2 - 1)}{\rho_s^2} \right] d\rho_s = \int_1^\infty \frac{2}{\rho_s^2} d\rho_s = -2 \int_1^\infty d\left(\frac{1}{\rho_s}\right) \\
 &= \left[-2\frac{1}{\rho_s} \right]_1^\infty = 2
 \end{aligned}$$

$$\begin{aligned}
 & \int_1^\infty \int_{\rho_s-1}^{\rho_s+1} \frac{\rho_s \cos \theta \rho_t^2}{\rho_s^2 \rho_t^2} d\rho_s d\rho_t = \iint \frac{1}{\rho_s^2} \frac{(1 + \rho_s^2 - \rho_t^2)}{2} d\rho_t d\rho_s \\
 &= \int_1^\infty \int_{\rho_s-1}^{\rho_s+1} \frac{1}{\rho_s^2} \frac{1}{2} \left[\frac{(1 + \rho_s^2)}{\rho_t^2} - 1 \right] d\rho_t d\rho_s = \int_1^\infty \frac{1}{\rho_s^2} \left[\frac{(1 + \rho_s^2)2}{\rho_s^2 - 1} - 2 \right] d\rho_s \\
 &= \int_1^\infty \frac{2}{\rho_s^2} [1 + \rho_s^2 - \rho_s^2 + 1] d\rho_s \\
 &= \int_1^\infty \frac{2}{\rho_s^2} d\rho_s = 2 \left[-\frac{1}{\rho_s} \right]_1^\infty = -2
 \end{aligned}$$

$$\therefore \int_1^\infty \int_{\rho_s-1}^{\rho_s+1} \cos \theta [(\rho_s^2 - 1) + \rho_t^2] \frac{d\rho_s d\rho_t}{\rho_s^2 \rho_t^2} = 2 - 2 = 0$$

Then, finally Eq. (13.16) for the total angular momentum about C is

$$\mathbf{G}_a = \frac{q_t q_s}{4\pi \varepsilon_0 c^2} \frac{1}{2} \left\{ \mathbf{R}_t \times \left[\frac{\mathbf{v}_s}{r} + \frac{(\mathbf{v}_s \cdot \mathbf{r}_{st}) \mathbf{r}_{st}}{r^3} \right] + \mathbf{R}_s \times \left[\frac{\mathbf{v}_t}{r} + \frac{(\mathbf{v}_t \cdot \mathbf{r}_{st}) \mathbf{r}_{st}}{r^3} \right] \right\} \quad (13.18)$$

To quote Page and Adams (1945, 144), "we see that the portion of the linear momentum involving the velocity \mathbf{v}_s of particle q_s is to be considered as located at the position of particle q_t which has velocity \mathbf{v}_t and vice versa."

13.2 Proca Equations as Modified Maxwell Equations

For a massive field we apply

$$(\square - M) \text{ to } (\mathbf{A} + \square\theta) \quad (13.19)$$

$$\begin{aligned} \square - M (\mathbf{A} + \square\theta) &= \square\mathbf{A} + \square(\square\theta) - M\mathbf{A} - M\square\theta \\ &= \square \wedge \mathbf{A} + \square \bullet \mathbf{A} + \square^2\theta - M\mathbf{A} - M\square\theta \\ &= \mathbf{F} + \square \bullet \mathbf{A} + \square^2\theta - M(\mathbf{A} + \square\theta) \end{aligned} \quad (13.20)$$

Where, as for E and M

$$\begin{aligned} \mathbf{F} &= \square\mathbf{A} = \mathbf{e}_0\mathbf{e}_1 \left(-\frac{\partial A_1}{c\partial t} - \frac{\partial A_0}{\partial x} \right) + \mathbf{e}_0\mathbf{e}_2 \left(-\frac{\partial A_2}{c\partial t} - \frac{\partial A_0}{\partial y} \right) + \mathbf{e}_0\mathbf{e}_3 \left(-\frac{\partial A_3}{c\partial t} - \frac{\partial A_0}{\partial z} \right) \\ &\quad + \mathbf{e}_1\mathbf{e}_2 \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) + \mathbf{e}_3\mathbf{e}_1 \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) + \mathbf{e}_2\mathbf{e}_3 \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) \\ &= (\mathbf{e}_0\mathbf{e}_1 E_x + \mathbf{e}_0\mathbf{e}_2 E_y + \mathbf{e}_0\mathbf{e}_3 E_z) / c + \mathbf{e}_1\mathbf{e}_2 B_x + \mathbf{e}_3\mathbf{e}_1 B_y + \mathbf{e}_2\mathbf{e}_3 B_z \end{aligned}$$

As in electromagnetism, we have put

$$\square \bullet \mathbf{A} + \square^2\theta = 0 \text{ or } \square \bullet \mathbf{A} = 0 \text{ and } \square^2\theta = 0$$

Then

$$(\square - M) (\mathbf{A} + \square\theta) = \mathbf{F} - M (\mathbf{A} + \square\theta) \quad (13.21)$$

Now apply $\square - M$ again and put $\square \bullet \mathbf{F} = -\mu_0 \mathbf{J}$

$$\begin{aligned} (\square - M) [\mathbf{F} - M(\mathbf{A} + \square\theta)] &= \square\mathbf{F} - M\square\mathbf{A} - M\square^2\theta - M\mathbf{F} + M^2\mathbf{A} + M\square\theta \\ &= \square\mathbf{F} + M^2\mathbf{A} - 2M\mathbf{F} + M\square\theta \end{aligned} \quad (13.22)$$

since $\square\mathbf{A} = \mathbf{F}$ and we take $\square\theta = 0$, then $\square^2\theta = 0$. The term $2M\mathbf{F} = \text{Biv}$, the EM field bivector, adds nothing new, therefore we drop it.

$$\begin{aligned} \square\mathbf{F} &= \mathbf{e}_0 \left(-\frac{\partial E_x}{\partial x} - \frac{\partial E_y}{\partial y} - \frac{\partial E_z}{\partial z} \right) + \mathbf{e}_1 \left[\frac{\partial E_x}{c\partial t} - \left(\frac{\partial B_z}{\partial y} - \frac{\partial B_y}{\partial z} \right) \right] \\ &+ \mathbf{e}_2 \left[\frac{\partial E_x}{c\partial t} - \left(\frac{\partial B_x}{\partial z} - \frac{\partial B_z}{\partial x} \right) \right] + \mathbf{e}_3 \left[\frac{\partial E_z}{c\partial t} - \left(\frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} \right) \right] \\ &+ \mathbf{e}_0\mathbf{e}_1\mathbf{e}_2 \left[-\left(\frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} \right) - \frac{\partial B_z}{\partial t} \right] + \mathbf{e}_0\mathbf{e}_3\mathbf{e}_1 \left[-\left(\frac{\partial E_x}{\partial z} - \frac{\partial E_z}{\partial x} \right) - \frac{\partial B_y}{\partial t} \right] \\ &+ \mathbf{e}_0\mathbf{e}_2\mathbf{e}_3 \left[-\left(\frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z} \right) - \frac{\partial B_x}{\partial t} \right] + \mathbf{e}_1\mathbf{e}_2\mathbf{e}_3 \left(\frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} \right) \\ &= \square \bullet \mathbf{F} + \square \wedge \mathbf{F} \end{aligned} \quad (13.23)$$

As in \mathbf{E} and \mathbf{M}

$$\square \bullet \mathbf{F} = -\mu_0 \mathbf{J} = -\mu_0 c \rho \mathbf{e}_0 - \mu_0 J_x - \mu_0 J_y - \mu_0 J_z \quad (13.24)$$

Putting the right hand side of Eq. (13.22) equal to $-\mu_0 \mathbf{J}$ and equating coefficients of the unit vectors, we obtain

$$\begin{aligned} -\text{div } \mathbf{E} - M^2 A_0 &= -\mu_0 c \rho \\ -(\text{curl } \mathbf{B})_x + \frac{\partial E_x}{c\partial t} + M^2 A_1 &= -\mu_0 j_x \\ -(\text{curl } \mathbf{B})_y + \frac{\partial E_y}{c\partial t} + M^2 A_2 &= -\mu_0 j_y \\ -(\text{curl } \mathbf{B})_z + \frac{\partial E_z}{c\partial t} + M^2 A_3 &= -\mu_0 j_z \\ \text{or } \text{div } E - M^2 A_0 &= \frac{\rho}{\varepsilon_0} \\ (\text{curl } \mathbf{B})_x - \frac{\partial E_x}{c\partial t} - M^2 A_1 &= \mu_0 j_x \\ (\text{curl } \mathbf{B})_y - \frac{\partial E_y}{c\partial t} - M^2 A_2 &= \mu_0 j_y \\ (\text{curl } \mathbf{B})_z - \frac{\partial E_z}{c\partial t} - M^2 A_3 &= \mu_0 j_z \end{aligned} \quad (13.25)$$

or

$$\begin{aligned}\operatorname{div} \mathbf{E} - M^2 A_0 &= \frac{\rho}{\varepsilon_0} \\ \operatorname{curl} \mathbf{B} - M^2 \mathbf{A} &= \mu_0 \mathbf{j}\end{aligned}\quad (13.26)$$

The $\square \wedge F = 0$ equations are the same as E and M , namely

$$\begin{aligned}\operatorname{div} \mathbf{B} &= 0 \\ \operatorname{curl} \mathbf{E} &= -\frac{\partial \mathbf{B}}{\partial t}\end{aligned}\quad (13.27)$$

Eqs. (13.26) and (13.27) are the Proca field equations.

In Eqs. (13.26) and (13.27) we express the field quantities \mathbf{E} and \mathbf{B} in terms of their definitions

$$\begin{aligned}\frac{E_x}{c} &= -\frac{\partial A_0}{\partial x} - \frac{\partial A_1}{c \partial t} & B_x &= \frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \\ \frac{E_y}{c} &= -\frac{\partial A_0}{\partial y} - \frac{\partial A_2}{c \partial t} & B_y &= \frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \\ \frac{E_z}{c} &= -\frac{\partial A_0}{\partial z} - \frac{\partial A_3}{c \partial t} & B_z &= \frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y}\end{aligned}$$

to obtain

$$\begin{aligned}& \frac{\partial}{\partial x} \left(-\frac{\partial A_0}{\partial x} - \frac{\partial A_1}{\partial t} \right) + \frac{\partial}{\partial y} \left(-\frac{\partial A_0}{\partial y} - \frac{\partial A_2}{\partial t} \right) + \frac{\partial}{\partial z} \left(-\frac{\partial A_0}{\partial z} - \frac{\partial A_3}{\partial t} \right) \\ + & \frac{\partial^2 A_0}{c^2 \partial t^2} - \frac{\partial^2 A_0}{c^2 \partial t^2} - M^2 A_0 = \frac{\rho}{\varepsilon_0} \\ & \frac{\partial}{\partial y} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) - \frac{\partial}{\partial z} \left(\frac{\partial A_1}{\partial z} - \frac{\partial A_3}{\partial x} \right) - \frac{\partial}{c \partial t} \left(-\frac{\partial A_0}{\partial x} - \frac{\partial A_1}{c \partial t} \right) \\ + & \frac{\partial^2 A_1}{\partial x^2} - \frac{\partial^2 A_1}{\partial x^2} - M^2 A_1 = \mu_0 j_x \\ & \frac{\partial}{\partial z} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) - \frac{\partial}{\partial x} \left(\frac{\partial A_2}{\partial x} - \frac{\partial A_1}{\partial y} \right) - \frac{\partial}{c \partial t} \left(-\frac{\partial A_0}{\partial y} - \frac{\partial A_2}{c \partial t} \right) \\ + & \frac{\partial^2 A_2}{\partial y^2} - \frac{\partial^2 A_2}{\partial y^2} - M^2 A_2 = \mu_0 j_y\end{aligned}$$

$$\begin{aligned}
 & \frac{\partial}{\partial x} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_1}{\partial z} \right) - \frac{\partial}{\partial y} \left(\frac{\partial A_3}{\partial y} - \frac{\partial A_2}{\partial z} \right) - \frac{\partial}{\partial t} \left(-\frac{\partial A_0}{\partial z} - \frac{\partial A_0}{\partial t} \right) \\
 & + \frac{\partial^2 A_3}{\partial z^2} - \frac{\partial^2 A_3}{\partial z^2} - M^2 A_3 = \mu_0 j_z
 \end{aligned}$$

where we have added and subtracted a term on each line to obtain

$$\begin{aligned}
 & - \left[\frac{\partial^2 A_0}{\partial x^2} + \frac{\partial^2 A_0}{\partial y^2} + \frac{\partial^2 A_0}{\partial z^2} + \frac{\partial^2 A_0}{c^2 \partial t^2} \right] - \frac{\partial}{\partial t} \left[\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} + \frac{\partial A_0}{\partial t} \right] - M^2 A_0 = \frac{\rho}{\varepsilon_0} \\
 & - \left[\frac{\partial^2 A_1}{\partial x^2} + \frac{\partial^2 A_1}{\partial y^2} + \frac{\partial^2 A_1}{\partial z^2} + \frac{\partial^2 A_1}{c^2 \partial t^2} \right] - \frac{\partial}{\partial x} \left[\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} + \frac{\partial A_0}{\partial t} \right] - M^2 A_1 = \mu_0 j_x \\
 & - \left[\frac{\partial^2 A_2}{\partial x^2} + \frac{\partial^2 A_2}{\partial y^2} + \frac{\partial^2 A_2}{\partial z^2} + \frac{\partial^2 A_2}{c^2 \partial t^2} \right] - \frac{\partial}{\partial y} \left[\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} + \frac{\partial A_0}{\partial t} \right] - M^2 A_2 = \mu_0 j_y \\
 & - \left[\frac{\partial^2 A_3}{\partial x^2} + \frac{\partial^2 A_3}{\partial y^2} + \frac{\partial^2 A_3}{\partial z^2} + \frac{\partial^2 A_3}{c^2 \partial t^2} \right] - \frac{\partial}{\partial z} \left[\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} + \frac{\partial A_0}{\partial t} \right] - M^2 A_3 = \mu_0 j_z
 \end{aligned}$$

Putting $\frac{\partial A_0}{\partial t} + \frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} = \square \bullet A = 0$, we obtain

$$\begin{aligned}
 \square^2 A_0 + M^2 A_0 &= -\frac{\rho}{\varepsilon_0} \\
 \square^2 A_1 + M^2 A_1 &= -\mu_0 j_x \\
 \square^2 A_2 + M^2 A_2 &= -\mu_0 j_y \\
 \square^2 A_3 + M^2 A_3 &= -\mu_0 j_z
 \end{aligned}$$

If the time dependence in \square^2 is ignored so $\square^2 \rightarrow \nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$ and replace ρ by q , the equations become

$$\begin{aligned}
 \nabla^2 A_0 + M^2 A_0 &= -\frac{q}{\varepsilon_0} \\
 \nabla^2 A_1 + M^2 A_1 &= -\mu_0 j_x \\
 \nabla^2 A_2 + M^2 A_2 &= -\mu_0 j_y \\
 \nabla^2 A_3 + M^2 A_3 &= -\mu_0 j_z
 \end{aligned}$$

To obtain a decreasing function in r for A_0 we need to replace M^2 by $-M^2$. To achieve this, replace M at the beginning by iM or $\mathbf{e}_5 M$. We choose the latter. The equation for A_0 which we now call Φ becomes

$$\nabla^2 \phi - M^2 \Phi = q$$

The spherically symmetric solution (Yukawa form) is

$$\phi(r) = -\frac{qe^{-M/r}}{r}.$$

All of the force interaction equations that follow from the Coulomb potential used to describe gravity will apply to Yukawa potential forces by differentiating the Yukawa potential respect to r and using the result along with the form of the velocity interactions that appear in the modified electromagnetic interactions that describe gravitational forces.